

# On the Shape of things From holography to elastica

Álvaro Véliz-Osorio (Jagiellonian University) Tehran May 2017

#### Based on 1611.03462 with:



#### Piermarco Fonda (Leiden)



Vishnu Jejjala (Wits)

...and work in progress

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# General question

Which shape a manifold is compelled to take when immersed in another one, provided it must extremize some functional?

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This question has been around for a while  $\sim 2000 \ {\rm years}$ 

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Did Virgilio forsee Ryu-Takayanagi?!?!

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# Geometric setup

Immersion  $f: N \rightarrow (M, g)$ 

$$\Sigma = \{x^{\mu}(\sigma_i) | i = 1, \dots, p\}$$

Indices:

Ambient  $\mu$ ,  $\nu = 1, \dots, d$ Tangent *i*,  $j = 1, \dots, p$ Normal A,  $B = 1, \dots, (d - p)$ 



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Induced metric

$$h_{ij} = g_{\mu
u} t^{\mu}_i t^{
u}_j$$

We can associate  $\tilde{\nabla}_i$ ,  $\mathcal{R}_{ijkl}$ ,  $\mathcal{R}$ , ...



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Projecting ambient tensors, example

$$R^{A}_{jik} = R_{\mu\nu\rho\sigma} n^{A\mu} t^{\nu}_{j} t^{\rho}_{j} t^{\sigma}_{j}$$

#### Extrinsic geometry

As one moves along  $\Sigma$ , how do normal vectors change?

$$t_i^{\nu} \nabla_{\nu} n^{\mu A} = K_{ij}^A t^{\mu j} - T_i^{AB} n_B^{\mu} ,$$

Extrinsic curvatures  $K_{ii}^A = t_i^\mu t_i^\nu \nabla_\mu n_\nu^A$ 

 $T_i^{AB} = t_i^{\mu} n^{\nu A} \nabla_{\mu} n_{\nu}^{B}$ Extrinsic torsions

Gauss relation

$$\mathcal{R}_{jkil} = R_{jkil} + K^{A}_{[ij}K^{B}_{kl}\eta_{AB}$$

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## Extrinsic geometry

As one moves along  $\Sigma$ , how do normal vectors change?

$$t_i^{\nu} \nabla_{\nu} n^{\mu A} = K_{ij}^A t^{\mu j} - T_i^{AB} n_B^{\mu} ,$$

Extrinsic curvatures

Extrinsic torsions

$$\begin{aligned} \mathcal{K}_{ij}^{A} &= t_{i}^{\mu} t_{j}^{\nu} \nabla_{\mu} n_{\nu}^{A} \\ \mathcal{T}_{i}^{AB} &= t_{i}^{\mu} n^{\nu A} \nabla_{\mu} n_{\nu}^{B} \end{aligned}$$

Gauss relation

$$\mathcal{R}_{jkil} = \mathcal{R}_{jkil} + \mathcal{K}^{\mathcal{A}}_{[ij}\mathcal{K}^{\mathcal{B}}_{kl]}\eta_{\mathcal{AB}}$$

Contracted

$$\mathcal{R} = R - 2R_{A}^{A} + R_{AB}^{AB} + \mathrm{Tr}\mathcal{K}_{A}\mathrm{Tr}\mathcal{K}^{A} - \mathrm{Tr}(\mathcal{K}_{A}\mathcal{K}^{A})$$

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Contains the *Theorema egregium*  $\mathcal{R} = 2 \det K_i^j$ 

# Gauge theory and the normal frame



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# Gauge theory and normal bundle

Under gauge transformations,  $n^B_\mu 
ightarrow \mathcal{M}^A_B n^B_\mu$ 

$$\mathcal{K}^{\mathcal{A}}_{ij} \to \mathcal{M}^{\mathcal{A}}_{\mathcal{B}} \mathcal{K}^{\mathcal{B}}_{ij} \qquad \mathcal{T}^{\mathcal{A}\mathcal{B}}_{i} \to \mathcal{M}^{\mathcal{C}}_{\mathcal{A}} \mathcal{M}^{\mathcal{D}}_{\mathcal{B}} \ \mathcal{T}^{\mathcal{A}\mathcal{B}}_{i} + \eta^{\mathcal{A}\mathcal{B}} \mathcal{M}^{\mathcal{C}}_{\mathcal{A}} \partial_{i} \mathcal{M}^{\mathcal{D}}_{\mathcal{B}}$$

 $T_i^{AB}$  transform as connections

Introduce a covariant derivative

$$\tilde{D}_{i\ B}^{A}V_{j\ldots}^{B}\equiv\tilde{\nabla}_{i}V_{j\ldots}^{B}+T_{i}^{AB}\eta_{BC}V_{j\ldots}^{C}$$

Gauge theory technology can be imported Interesting to combine with geometric identities, Ex:

$$F_{ij}^{AB} = K^A_{[ik}K^B_{j]l}h^{kl} - R^{AB}_{ij}$$

# A simple and beautiful example

A surface in a three dimensional manifold

$$S_0[\Sigma] = \lambda_0 \int_{\Sigma} d^p \sigma \ \sqrt{h} \ 1 = \lambda_0 \operatorname{Area}[\Sigma] \ .$$

Moving away in a normal direction

$$\mathcal{L}_n h_{ij} = 2\varepsilon K_{ij}$$
,

The first shape equation

$$\mathrm{Tr}K_{ij}=0$$



When minimising its area a surface makes each of its point a saddle whose directions have the exact opposite curvature.

#### A beautiful fact indeed!!

Generalizations of the area functional

$$S_0[\Sigma] = \lambda_0 \int_{\Sigma} d^p \sigma \ \sqrt{h} \ 1 = \lambda_0 \operatorname{Area}[\Sigma] \ .$$

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Ex: Willmore functional, Canham-Helfrich, Dong functional, ...

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Contributions at second order

 $\lambda_{1}\mathcal{R} + \lambda_{2}\mathcal{R} + \lambda_{3}\mathcal{R}_{A}^{A} + \lambda_{4}\mathcal{R}_{AB}^{AB} + \lambda_{5}\mathrm{Tr}\mathcal{K}_{A}\mathrm{Tr}\mathcal{K}^{A} + \lambda_{6}\mathrm{Tr}\mathcal{K}^{A}\mathcal{K}_{A}$ 

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They aren't all independent, since

 $\mathcal{R} = R - 2R_A^A + R_{AB}^{AB} + \mathrm{Tr} K_A \mathrm{Tr} K^A - \mathrm{Tr} (K_A K^A)$ 

Generalizations of the area functional

$$S_0[\Sigma] = \lambda_0 \int_{\Sigma} d^p \sigma \ \sqrt{h} \ 1 = \lambda_0 \operatorname{Area}[\Sigma] \ .$$

Ex: Willmore functional, Canham-Helfrich, Dong functional, ...

Contributions at second order

$$\lambda_{1}\mathcal{R} + \lambda_{2}\mathcal{R} + \lambda_{3}\mathcal{R}_{A}^{A} + \lambda_{4}\mathcal{R}_{AB}^{AB} + \lambda_{5}\mathrm{Tr}\mathcal{K}_{A}\mathrm{Tr}\mathcal{K}^{A} + \lambda_{6}\mathrm{Tr}\mathcal{K}^{A}\mathcal{K}_{A}$$

# Mission: find the extrema of this functional

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# Topological terms

For a curve in three dimensions

$$\tau = \frac{1}{2} \epsilon_{AB} T^{AB}$$

For a surface in four dimensions

$$\varphi = \frac{1}{4} \epsilon_{AB} \epsilon^{ij} F^{AB}_{ij}$$

Three-dimensional submanifolds

$$\Phi = \epsilon^{ijk} \eta_{AC} \left( F^A_{ijB} T^{BC}_k - \frac{1}{3} T^A_{iB} T^B_{jD} T^{DC}_k \right)$$

Important when studying EE for TMG or CS-gravity

Castro, Detournay, Iqbal, Perlmutter '14 Azeyanagi, Logayagam, Ng '15 Ali, Haque, Murugan '16

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Some of interesting cases:

• Minimal submanifolds  $\lambda_0 \neq 0$ 

$$\operatorname{Tr} K^A = 0$$

• Generalized Willmore  $\lambda_5 \neq 0$ 

 $\mathrm{Tr}\mathcal{K}_{\mathcal{B}}\left[\mathrm{Tr}\mathcal{K}^{\mathcal{A}}\mathrm{Tr}\mathcal{K}^{\mathcal{B}}-2\mathrm{Tr}\left(\mathcal{K}^{\mathcal{B}}\mathcal{K}^{\mathcal{A}}\right)-2\mathcal{R}_{i}^{\mathcal{B}}{}_{i}^{\mathcal{A}i}\right]-2\tilde{D}_{i}{}_{\mathcal{C}}^{\mathcal{B}}\tilde{D}^{i\mathcal{C}\mathcal{A}}\mathrm{Tr}\mathcal{K}_{\mathcal{B}}=0$ 

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...in their full glory

### Shape equations

For arbitrary dimension and codimension, the extrema of the second order functional obey

$$\mathcal{E}^{A} = \lambda_{0} \mathrm{Tr} \mathcal{K}^{A} + \sum_{n=1}^{6} \lambda_{n} \mathcal{E}^{A}_{n} = 0$$

with

$$\begin{split} \mathcal{E}_{1}^{A} &= \operatorname{Tr} \mathcal{K}^{A} \mathcal{R} - 2 \mathcal{R}^{ij} \mathcal{K}_{ij}^{A}, \\ \mathcal{E}_{2}^{A} &= \operatorname{Tr} \mathcal{K}^{A} \mathcal{R} + n_{\mu}^{A} \nabla^{\mu} \mathcal{R}, \\ \mathcal{E}_{3}^{A} &= \operatorname{Tr} \mathcal{K}^{A} \mathcal{R}_{B}^{\ B} + 2 \tilde{D}_{k}^{\ BA} \mathcal{R}_{B}^{k} + n_{C}^{\mu} n^{C\nu} n^{A\delta} \nabla_{\delta} \mathcal{R}_{\mu\nu}, \\ \mathcal{E}_{4}^{A} &= \operatorname{Tr} \mathcal{K}^{A} \mathcal{R}_{CB}^{\ CB} + 4 \tilde{D}_{k}^{\ BA} \mathcal{R}_{BC}^{kC} + n_{C}^{\mu} n_{B}^{\nu} n^{C\rho} n^{B\sigma} n^{A\delta} \nabla_{\delta} \mathcal{R}_{\mu\nu\rho\sigma}, \\ \mathcal{E}_{5}^{A} &= \operatorname{Tr} \mathcal{K}_{B} \left[ \operatorname{Tr} \mathcal{K}^{A} \operatorname{Tr} \mathcal{K}^{B} - 2 \operatorname{Tr} \left( \mathcal{K}^{B} \mathcal{K}^{A} \right) - 2 \mathcal{R}_{i}^{B} \mathcal{A}^{i} \right] - 2 \tilde{D}_{i}^{\ B} \mathcal{L}_{O}^{DiCA} \operatorname{Tr} \mathcal{K}_{B}, \\ \mathcal{E}_{6}^{A} &= \operatorname{Tr} \mathcal{K}^{A} \operatorname{Tr} \left( \mathcal{K}_{B} \mathcal{K}^{B} \right) - 2 \left[ \tilde{D}_{i}^{\ C} \mathcal{D}_{j}^{\ BA} \mathcal{K}_{C}^{ij} + \operatorname{Tr} \left( \mathcal{K}^{B} \mathcal{K}_{B} \mathcal{K}^{A} \right) + \mathcal{K}_{B}^{ij} \mathcal{R}_{i}^{B} \mathcal{A}_{i}^{i} \right], \end{split}$$

# Shape equations in maximally symmetric spaces

Suppose that the ambient has

$$R_{\mu
u
ho\sigma} = rac{R}{d(d-1)} \left( g_{\mu
ho} g_{
u\sigma} - g_{\mu\sigma} g_{
u
ho} 
ight) \qquad R = {
m const}$$

with

$$R=\kappa rac{d(d-1)}{L^2}\;,\qquad \kappa=0,\pm 1\;.$$

Minimal submanifolds are extrema if

$$\lambda_1 = \lambda_6$$
 or  $\mathcal{R}^{ij} \mathcal{K}^{\mathcal{A}}_{ij} = 0$ .

The second condition is true for curves  $\mathcal{R}^{ij} = 0$  and surfaces

$$\mathcal{R}^{ij}K^{A}_{ij} = \frac{\mathcal{R}}{2}\mathrm{Tr}K^{A} = 0$$

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For p > 2, minimal submanifolds are NOT necessarily extrema

Considering a curve  $\gamma$  in  $\mathbb{R}^2$ ,  $\mathbb{S}^2$  or  $\mathbb{H}^2$ 

#### Reminiscences

 $ln[16]:= eomf = VariationalD[\mathcal{L}[\phi[r]], \phi[r], r] // FullSimplify$ simplifica completant

 $\begin{aligned} & \text{Out[16]=} \frac{1}{\text{L}^2 \ (\text{L}^2 + \text{r}^4 \ \phi'[\,\text{r}\,]^2\,)^4 \ \sqrt{\frac{\text{L}^2 + \text{r}^4 \ \phi'[\,\text{r}\,]^2}{\text{r}^2}}} \\ & \text{r} \ \left(-\text{L}^2 \ \lambda_0 \ \left(\text{L}^2 + \text{r}^4 \ \phi'[\,\text{r}\,]^2\,\right)^3 \ \left(3 \ \text{L}^2 \ \phi'[\,\text{r}\,] + \text{r}^4 \ \phi'[\,\text{r}\,]^3 + \text{L}^2 \ \text{r} \ \phi''[\,\text{r}\,]\right) +} \\ & \lambda_5 \ \left(75 \ \text{L}^4 \ \text{r}^8 \ \phi'[\,\text{r}\,]^5 - 3 \ \text{L}^2 \ \text{r}^{12} \ \phi'[\,\text{r}\,]^7 - \text{r}^{16} \ \phi'[\,\text{r}\,]^9 + \text{L}^2 \ \text{r}^{13} \ \phi'[\,\text{r}\,]^6 \ \phi''[\,\text{r}\,] - \\ & 5 \ \text{L}^4 \ \text{r}^4 \ \phi'[\,\text{r}\,]^3 \ \left(37 \ \text{L}^2 + \text{r}^6 \ \phi''[\,\text{r}\,] \ (-15 \ \phi''[\,\text{r}\,] + 4 \ \text{r} \ \phi^{(3)}[\,\text{r}\,]\,)\right) + \\ & \text{L}^6 \ \phi'[\,\text{r}\,] \ \left(18 \ \text{L}^2 - 5 \ \text{r}^6 \ \phi''[\,\text{r}\,] \ (27 \ \phi''[\,\text{r}\,] + 4 \ \text{r} \ \phi^{(3)}[\,\text{r}\,]\,)\right) + \\ & \text{L}^4 \ \text{r}^5 \ \phi'[\,\text{r}\,]^2 \ \left(-267 \ \text{L}^2 \ \phi''[\,\text{r}\,] + 30 \ \text{r}^6 \ \phi''[\,\text{r}\,]^3 + 4 \ \text{L}^2 \ \text{r}^2 \ \phi^{(4)}[\,\text{r}\,]\,) + \\ & 2 \ \text{L}^4 \ \text{r}^9 \ \phi'[\,\text{r}\,]^4 \ \left(54 \ \phi''[\,\text{r}\,] + \text{r} \ (-10 \ \phi^{(3)}[\,\text{r}\,] + \text{r} \ \phi^{(4)}[\,\text{r}\,]\,)\,) + \\ & \text{L}^6 \ \text{r} \ \left(46 \ \text{L}^2 \ \phi''[\,\text{r}\,] - 5 \ \text{r}^6 \ \phi''[\,\text{r}\,]^3 + 2 \ \text{L}^2 \ \text{r} \ \left(10 \ \phi^{(3)}[\,\text{r}\,] + \text{r} \ \phi^{(4)}[\,\text{r}\,]\,)\,)\,) \right) \end{aligned}$ 

This is the shape equation for a curve in the Poincaré disk

Using the shape equations instead

$$2\tilde{\Delta}\mathrm{Tr}\mathbf{k} + \mathrm{Tr}\mathbf{k}^{3} - \left(\frac{\hat{\lambda}_{0}}{\lambda_{5}^{\prime}} - \frac{2\kappa}{L^{2}}\right)\mathrm{Tr}\mathbf{k} = 0$$

In arc-length parametrization

$$2\ddot{k} + k^3 - B k = 0$$
,  $B = \left(\frac{\hat{\lambda}_0}{\lambda'_5} - \frac{2\kappa}{L^2}\right)$ 

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Two-step splitting

- First find out the extrinsic curvature
- $\blacktriangleright$  Second invert this curvature to find  $\gamma$

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Perhaps this can be solved (?)

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Even these cannot be spotted straightaway in the old equation

Finding the extrinsic curvature

$$2\ddot{k} + k^3 - B k = 0$$
,  $B = \left(\frac{\hat{\lambda}_0}{\lambda'_5} - \frac{2\kappa}{L^2}\right)$ 

Simplest solutions, k = const

Geodesics k = 0 and CMC  $k^2 = B$ 

In fact, the full solution can be found !!

$$k^{2}(s) = \alpha \left[ 1 - rac{lpha - \gamma}{lpha} \mathrm{sn}^{2} (rac{1}{2} \sqrt{lpha - eta} \, s, \, rac{lpha - \gamma}{lpha - eta}) 
ight]$$

With  $\operatorname{sn}(z,m)$  a Jacobi elliptic function and lpha,  $\gamma$  and eta constants

Langer-Singer '84



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Possible behaviour for  $u(s) = k^2(s)$ 

- Orange: Constant mean curvature
- Red: Wavelike
- Blue: Orbitlike
- Green: Asymptotically geodesic

# Extrema in $\mathbb{H}^2$

Now, we must invert k(s)

This is rather involved, yet attainable analytically

For hyperbolic geometry  $\mathbb{H}^2$ 

$$ds^2 = \frac{1}{z^2} \left( dx^2 + dz^2 \right)$$

Wavy solutions in  $\mathbb{H}^2$  read

$$z(s) = \frac{C}{2+\lambda} \frac{\exp\left[\sqrt{C^2 - 4(\lambda+1)}\left(\frac{s}{4} - \frac{2(C-2)}{4\sqrt{2C(C+2)}}\Pi\left[n,\varphi(s);m\right]\right)\right]}{\sqrt{(C+2)^2 - 4(C+2+\lambda)\operatorname{sn}^2\left(\sqrt{\frac{C}{2}}s,\frac{C+2+\lambda}{2C}\right)}}$$

Where C and  $\lambda$  are constants, while

$$\varphi(s) = \operatorname{amp}\left(\sqrt{\frac{C}{2}}s, \frac{C+2+\lambda}{2C}\right)$$

# Extrema in $\mathbb{H}^2$



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# Application: holographic entanglement entropy

For field theories with an Einstein gravity dual

Area functional

$$S_{ ext{eff}}[\Sigma] = rac{1}{4G_d} \int_{\Sigma} d^p \sigma \, \sqrt{h}$$

Minimize

$$\operatorname{Tr} K^A = 0$$

Evaluate on-shell

$$S_{\mathrm{EE}}(A) = S_{\mathrm{eff}}^{\mathrm{on-shell}}[\Sigma]$$
.



Ryu, Takayanagi '06

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#### Application: holographic entanglement entropy

If the dual gravitational theory has h.c. corrections

$$\mathcal{L} = -2\Lambda + R + c_1 R^2 + c_2 R_{\mu\nu} R^{\mu\nu} + c_3 R_{\mu\nu\rho\sigma} R^{\mu\nu\rho\sigma}$$

Then the EE functional

$$\begin{split} S_{\text{eff}} &= \frac{1}{4G_d} \int_{\Sigma} d^p \sigma \sqrt{h} \Big[ 1 + 2c_1 R + c_2 \left( R_A{}^A - \frac{1}{2} \text{Tr} \mathcal{K}_A \text{Tr} \mathcal{K}^A \right) \\ &+ 2c_3 \left( R_{AB}{}^{AB} - \text{Tr} (\mathcal{K}^A \mathcal{K}_A) \right) \Big] \end{split}$$

Bhattacharrya, Sharma, Sinha; Camps; Dong '13

- To find the EE one must evaluate the functional on an extremum.
- Which of the possible extrema is not settled (minimal??)
- It would be nice to be able to scan the space of extrema.

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Clearly, the extrema are solutions to the shape equations

# Entanglement entropy AdS<sub>3</sub>

For a higher-derivative theory (such as NMG)



#### We know all the extrema

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# Entanglement entropy $AdS_3/CFT_2$

The EE for an interval is universal

$$\mathcal{S}_{ ext{EE}}(\mathcal{A}) = rac{c}{3} \log\left(rac{\ell}{\epsilon}
ight) + \mathcal{O}(\epsilon)$$

Holzhey, Larsen, Wilczek '94

Using the fact that

$$c = \frac{L}{2G_3} g^{\mu\nu} \frac{\partial \mathcal{L}}{\partial R_{\mu\nu}} \,,$$

Saida, Soda '00

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We show that

$$S_{\mathrm{EE}}(A) = S_{\mathrm{on-shell}}^{\mathrm{Geo}}[\Sigma],$$

Are geodesics minimal? Let's compare

$$\hat{S}_{\mathrm{on-shell}}[\Sigma] = \ell rac{d}{d\ell} \, S_{\mathrm{on-shell}}[\Sigma]$$

# Comparing on-shell values in NMG



The geodesic's on-shell value is the black one (**not** minimal)

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# Interesting questions

- If not minimality then which criterium?
- What if geodesics are not extrema?
- What about perturbations? or curvature driven flows?
- Is there an information theoretic interpretation of other extrema in terms of:
  - Length and differential entropy

Czech, Hayden, Lashkari, Swingle '14

The surface/state correspondece

Miyaji, Takayanagi '15

How far can we get in higher-dimensional settings?

Fonda, Véliz-Osorio .. in progress

How far can we get in less symmetric ambients?

.. sometimes you get homework

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# Anomalies and flows

## Chiral anomalies

The c-theorem for parity violating  $(c_L \neq c_R)$ 

$$T(z)T(0) \sim \frac{c_L/2}{z^4} + \frac{T(0)}{z^2} + \frac{\partial T(0)}{z} + \dots$$
  
$$\bar{T}(\bar{z})T(0) \sim \frac{c_R/2}{z^4} + \frac{T(0)}{z^2} + \frac{\partial T(0)}{z} + \dots$$

Along the flow

$$trac{d}{dt}\left(c_L(t)+c_R(t)
ight)\leq 0 \qquad trac{d}{dt}\left(c_L(t)-c_R(t)
ight)=0$$

Bastianelli, Lindström '96

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Holographically with Topologically Massive Gravity

$$c_L = rac{3\ell}{2G}\left(1+rac{1}{\mu\ell}
ight) \qquad c_R = rac{3\ell}{2G}\left(1-rac{1}{\mu\ell}
ight)$$

# Torsion and anomalies

For a theory with chiral anomaly  $(c_L \neq c_R)$ 

$$S_{\mathsf{EE}}[\Sigma] = \int_{\Sigma} d\sigma \sqrt{h} \left(\mathfrak{m} + \mathfrak{s} \, \tau\right)$$

Castro, Detournay, Iqbal, Perlmutter '14

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Shape equations

$$\mathfrak{m} K_{A} + \mathfrak{s} \epsilon_{AB} \left( \tilde{D}^{B}_{sC} K^{C} + R_{s}^{B} \right) = 0,$$

#### Torsion and anomalies

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Shape equations

$$\mathfrak{m} \, \mathcal{K}_{A} + \mathfrak{s} \, \epsilon_{AB} \left( \tilde{D}^{B}_{sC} \mathcal{K}^{C} + \mathcal{R}^{B}_{s} \right) = 0 \,,$$

For MSS spaces

$$\mathfrak{m}k_{FS}-\mathfrak{s}\tau_{FS}k_{FS}=0\qquad \mathfrak{s}k_{FS}=0$$

Solutions are nice!!

 $k_{FS} = \text{const} > 0$  and  $\tau_{FS} = \mathfrak{m}/\mathfrak{s}$ 

Castro, Fonda, Véliz-Osorio .. in progress

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# Curly extrema $\mathbb{H}_3$



#### Helices

 $x^{\mu}(s) = \frac{1}{\cosh\gamma\cosh\alpha s - \sinh\gamma\sin\beta s} \left(\cosh\gamma\sinh\alpha s, \sinh\gamma\cos\beta s, 1\right)$ 

# Curly extrema AdS<sub>3</sub>



#### Helices

 $x^{\mu}(s) = \frac{1}{\cosh\gamma\cosh\alpha s - \sinh\gamma\cosh\beta s} \left(\cosh\gamma\sinh\alpha s, \sinh\gamma\sinh\beta s, 1\right)$ 

The on-shell value

$$\mathcal{S}[\Sigma]^{\mathrm{Hel}}_{o.s.} = 2\mathfrak{m}\,\ell_{\mathrm{Hel}}(\Sigma) + \mathfrak{s}(\eta_f - \eta_i) \qquad \ell_{\mathrm{Hel}} pprox |lpha|^{-1}\log(\ell/arepsilon)$$

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TMG flows driven by a scalar  $\varphi(z)$ 

$$ds^2=rac{dz^2}{z^2f(z)}+rac{\eta_{ab}dx^adx^b}{z^2}\,.$$

Flowing shape equations

$$\mathfrak{m}K_{A} + \mathfrak{s}\,\epsilon_{AB}\tilde{D}^{B}_{s\,C}K^{C} = -\mathfrak{s}\epsilon_{AB}\,\partial^{B}\varphi\partial_{s}\varphi$$

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One can show that connected extrema must always curl

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Flowing curls are yet to be found

$$\tau_{\rm FS} = \frac{\mathfrak{m}}{\mathfrak{s}} - \eta^z \,\partial_s \log\left(k_{\rm FS}\right)$$
$$\dot{k}_{\rm FS} = \mu^z \,\,\varphi'(z)^2$$

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TMG flows driven by a scalar  $\varphi(z)$ 

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Flowing shape equations

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You'll be hearing from us ... stay tunned



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# Epilogue

# Elastica

Two interesting set-ups

Canham-Helfrich

 $p=2, M=\mathbb{R}^3$ 

$$\mathcal{L} = \left[\sigma + rac{k_c}{4} (\mathrm{Tr} \mathcal{K})^2 + ar{k}_c \det \mathcal{K}
ight]$$





Sadowsky-Wünderlich  $p = 2, M = \mathbb{R}^3$ 

$${\cal L} = rac{(k_{
m FS}^2 + au_{
m FS}^2)^2}{k_{
m FS}^2}\,.$$



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$${\cal L} = rac{(k_{
m FS}^2 + au_{
m FS}^2)^2}{k_{
m FS}^2}\,.$$

Judicious breaking of gauge invariance



# Interesting problems

Elastica in (evolving) surfaces



- Embeddings of embeddings, interface theory on surfaces
- Minimal surfaces bounded by elastic lines

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Giomi, Mahadevan '11
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• Conformal maps: Minimal in  $AdS_d \leftrightarrow Willmore$  in  $\mathbb{R}^3$ 

Alexakis, Mazzeo '10; Fonda, Seminara, Tonni '15

Generalized curvature flows

Fonda, Véliz-Osorio...in progress